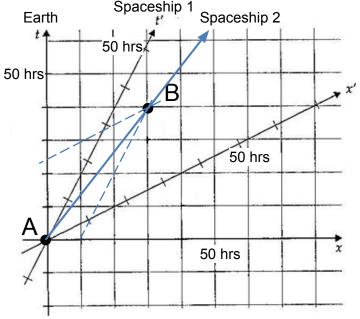
Lecture 30 (Velocity Transformations & Relativistic Dynamics)

Physics 2310-01 Spring 2020 Douglas Fields

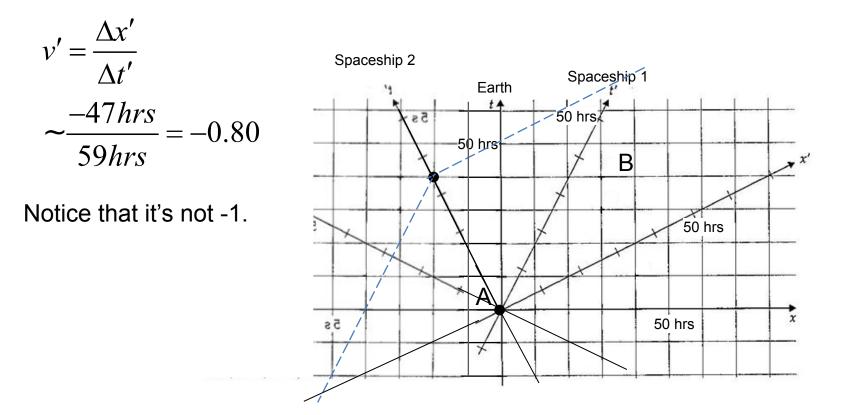
- Okay, let's look at how velocities transform between reference frames.
- Let's say we launch from earth two spaceships at the same time, one which travels at β =0.5 (spaceship 1), and one that travels at v=0.75 (spaceship 2), both relative to the earth.
- With what speed does spaceship 2 have relative to spaceship 1?
- Well, we can look at two events along the worldline of spaceship 2, labeled as event A (the launch from earth) and event B, and just ask what is Δx'/Δt':

$$v' = \frac{\Delta x'}{\Delta t'}$$
$$\sim \frac{10.5hrs}{26.5hrs} = 0.40$$

Notice that it's not 0.25.



• What if we have spaceship 2 travel in the opposite direction of spaceship 1, at v=-0.5?



- So, we can see that velocity transformations in Special Relativity are not trivial like they are in Newtonian Relativity. How would we express them mathematically?
- Let's use the Lorentz transformations:

$$v'_{x} = \frac{dx'}{dt'} = \frac{\gamma \left(dx - \beta dt \right)}{\gamma \left(dt - \beta dx \right)} = \frac{dx - \beta dt}{dt - \beta dx}$$
$$= \frac{\frac{dx}{dt} - \beta \frac{dt}{dt}}{\frac{dt}{dt} - \beta \frac{dt}{dt}} = \frac{v_{x} - \beta}{1 - \beta v_{x}}$$

- So far we have only considered velocities in the same direction as the relative velocity between the two frames.
- Are velocities in the transverse directions the same (v_v' = v_y, v_z' = v_z?
 Let's use the Lorentz transformations:

$$v'_{y} = \frac{dy'}{dt'} = \frac{dy}{\gamma \left(dt - \beta dx\right)}$$
$$= \frac{\frac{dy}{dt}}{\gamma \left(\frac{dt}{dt} - \beta \frac{dx}{dt}\right)} = \frac{v_{y} \sqrt{1 - \beta^{2}}}{1 - \beta v_{x}}$$

And the same for velocities in the z-direction

Velocity Transformations

• So our velocity transformations are:

$$v'_{x} = \frac{v_{x} - \beta}{1 - \beta v_{x}}, \quad v'_{y} = \frac{v_{y}\sqrt{1 - \beta^{2}}}{1 - \beta v_{x}}, \quad v'_{z} = \frac{v_{z}\sqrt{1 - \beta^{2}}}{1 - \beta v_{x}}$$

 And the inverse transformations are just given by substituting -β for β:

$$v_{x} = \frac{v'_{x} + \beta}{1 + \beta v'_{x}}, \quad v_{y} = \frac{v'_{y} \sqrt{1 - \beta^{2}}}{1 + \beta v'_{x}}, \quad v_{z} = \frac{v'_{z} \sqrt{1 - \beta^{2}}}{1 + \beta v'_{x}}$$

Consequence of Velocity Transformations

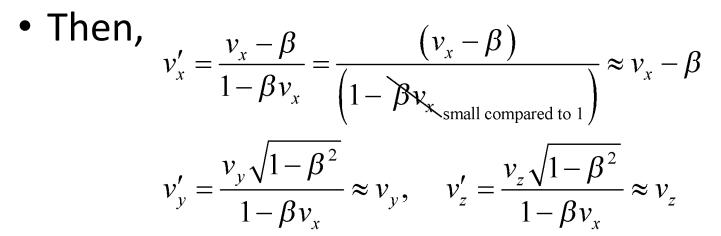
- Let's ask: "What is the speed of light in the different frames?"
- If the home frame measures 1 for the speed of light, what does a moving frame measure?

$$v'_{x} = \frac{v_{x} - \beta}{1 - \beta v_{x}} = \frac{1 - \beta}{1 - \beta \cdot 1} = 1$$

 Regardless of the relative velocity between frames!

Consequence of Velocity Transformations

 Let's ask: "What is the speed of something if the frames are moving slowly relative to one another?"



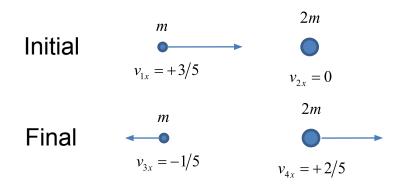
• Which is our Newtonian relativity!

Relativistic Dynamics

- So far, we have just explored the Special Relativistic analog of Chapter 1 in Physics 160.
- We just have our variables to measure distance and time, but we haven't yet seen how these translate to actions – how do objects behave when they act on each other.
- Newton's Laws, at their heart, deal with momentum, so let's first look at Newtonian momentum and see if it behaves well in our new paradigm.
- Newtonian momentum is just: $\vec{p} = m\vec{v}$
- Will this definition work in every inertial frame?

Conservation of Newtonian Momentum

• Let's look at the following example, where we look at a collision between two masses in the rest frame of one of them...

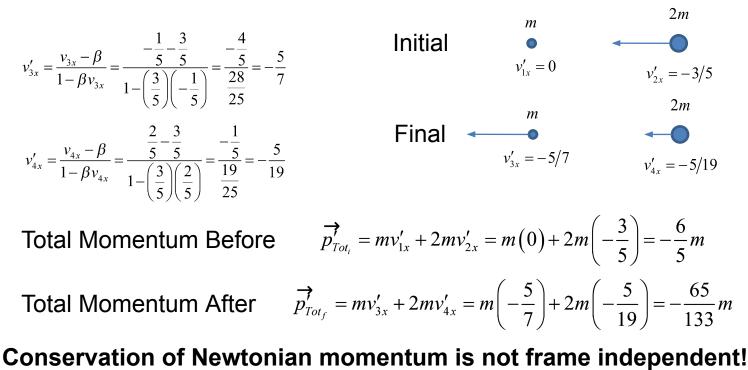


Total Momentum Before
$$\overrightarrow{p}_{Tot_i} = mv_{1x} + 2mv_{2x} = m\left(+\frac{3}{5}\right) + 2m(0) = +\frac{3}{5}m$$

Total Momentum After $\overrightarrow{p}_{Tot_f} = mv_{3x} + 2mv_{4x} = m\left(-\frac{1}{5}\right) + 2m\left(+\frac{2}{5}\right) = +\frac{3}{5}m$

Conservation of Newtonian Momentum

- Now, let's just move to a frame that is moving along with the other particle.
- We will use the SR velocity transformation equations we just derived....

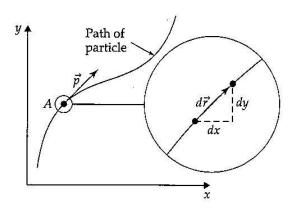


Four Momentum

- Rather than giving up on the idea of momentum conservation, we need to look for a new definition of momentum that:
 - Gives us back Newtonian momentum at low speeds
 - Gives us momentum conservation when at relativistic speeds
 - It might even give us something more...
- There are many ways to derive the idea of relativistic momentum (see Special Relativity: A Modern Introduction by H.C. Ohanian for a more mathematically rigorous derivation).
- I will follow Moore's (Six Ideas that Shaped Physics, Volume R) derivation, which is more conceptual...
- Let's first look at the concept of Newtonian momentum:

$$\overrightarrow{p} = \overrightarrow{mv} = m \frac{\overrightarrow{dr}}{dt} = m \left[\frac{dx}{dt}, \frac{dy}{dt}, \frac{dz}{dt} \right]$$

Newtonian momentum is tangent to the particle's **path** and involves the **time** derivative of each of its **three** dimensions, times its mass.

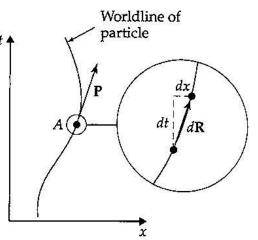


Four Momentum

- Now that we have discovered that time and space are tied together in spacetime, we want to give *time* an equal place with *space* in our momentum definition.
- Also, since time is not invariant by itself, rather than taking the time derivative, *dt* (which is different for different frames), we will take the derivative with respect to the proper time, *dτ*, which is frame independent.

$$\mathbf{P} = m \frac{d\mathbf{R}}{d\tau} = m \left[\frac{dt}{d\tau}, \frac{dx}{d\tau}, \frac{dy}{d\tau}, \frac{dz}{d\tau} \right]$$

Relativistic momentum is tangent to the particle's **worldline** and involves the **proper time** derivative of each of its **four** dimensions, times its mass.



Four Momentum

• Let's take a closer look at the components of the Four Momentum four-vector with the substitution: $d\tau = \sqrt{1-v^2} dt$

• Finally, we get that:

$$\mathbf{P} = \left[\frac{m}{\sqrt{1 - v^2}}, \frac{mv_x}{\sqrt{1 - v^2}}, \frac{mv_y}{\sqrt{1 - v^2}}, \frac{mv_z}{\sqrt{1 - v^2}}\right]$$

$$\mathbf{P} = m \frac{d\mathbf{R}}{d\tau} = m \left[\frac{dt}{d\tau}, \frac{dx}{d\tau}, \frac{dy}{d\tau}, \frac{dz}{d\tau} \right]$$

$$P_t = m \frac{dt}{d\tau} = m \frac{dt}{\sqrt{1 - v^2} dt} = \frac{m}{\sqrt{1 - v^2}}$$

$$P_x = m \frac{dx}{d\tau} = m \frac{dx}{\sqrt{1 - v^2} dt} = \frac{mv_x}{\sqrt{1 - v^2}}$$

$$P_y = m \frac{dy}{d\tau} = m \frac{dy}{\sqrt{1 - v^2} dt} = \frac{mv_y}{\sqrt{1 - v^2}}$$

$$P_z = m \frac{dz}{d\tau} = m \frac{dz}{\sqrt{1 - v^2} dt} = \frac{mv_z}{\sqrt{1 - v^2}}$$

What is v???

Frame Transformations of the Four Momentum

 How does the Four Momentum four-vector transform between reference frames?

$$\begin{aligned} \mathbf{P} &= m \frac{d\mathbf{R}}{d\tau} = m \left[\frac{dt}{d\tau}, \frac{dx}{d\tau}, \frac{dy}{d\tau}, \frac{dz}{d\tau} \right] \\ P_t' &= m \frac{dt'}{d\tau} = m \frac{\gamma \left(dt - \beta dx \right)}{\sqrt{1 - v^2} dt} = m \frac{\gamma \left(\frac{dt}{dt} - \beta \frac{dx}{dt} \right)}{\sqrt{1 - v^2} \frac{dt}{dt}} = \gamma \left[\frac{m}{\sqrt{1 - v^2}} - \frac{\beta m v_x}{\sqrt{1 - v^2}} \right] = \gamma \left(P_t - \beta P_x \right) \\ P_x' &= m \frac{dx'}{d\tau} = m \frac{\gamma \left(dx - \beta dt \right)}{\sqrt{1 - v^2} dt} = \gamma \left[\frac{m v_x}{\sqrt{1 - v^2}} - \frac{\beta m}{\sqrt{1 - v^2}} \right] = \gamma \left(P_x - \beta P_t \right) \\ P_y' &= m \frac{dy'}{d\tau} = m \frac{dy}{\sqrt{1 - v^2} dt} = \frac{m v_y}{\sqrt{1 - v^2}} = P_y \\ P_z' &= m \frac{dz'}{d\tau} = m \frac{dz}{\sqrt{1 - v^2} dt} = \frac{m v_z}{\sqrt{1 - v^2}} = P_z \end{aligned}$$

Frame Transformations of the Four Momentum

- So, the Four Momentum transforms exactly as the spacetime coordinates.
- Just use the Lorentz transformations:

$$\mathbf{R} = \begin{bmatrix} dt, dx, dy, dz \end{bmatrix} \qquad \mathbf{P} = m \frac{d\mathbf{R}}{d\tau} = m \begin{bmatrix} \frac{dt}{d\tau}, \frac{dx}{d\tau}, \frac{dy}{d\tau}, \frac{dz}{d\tau} \end{bmatrix}$$
$$dt' = \gamma (dt - \beta dx) \qquad P'_t = \gamma (P_t - \beta P_x)$$
$$dx' = \gamma (dx - \beta dt) \qquad P'_x = \gamma (P_x - \beta P_t)$$
$$dy' = dy \qquad P'_y = P_y$$
$$dz' = dz \qquad P'_z = P_z$$